

TensorFlow

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0.1 Context

TensorFlow has rapidly grown in popularity due to the fact that is developed/supported by Google. As more and more developers move to the platform, it becomes essential to learn how it works and have a general idea of the various concepts it makes use of. This is a short article about some of these concepts.

0.2 Learned in this study

0.3 Things to explore

1 Overview

- Computations are represented as graphs
- Graphs are executed in the context of `Sessions`

2 Building a graph

- Start with ops that do not need any input (called `source ops`), such as `Constant`

3 Session

- Graphs are executed within a session (context)
`session = tf.Session()`
- Sessions are given one or many tensor to resolve
`session.run([tensorA, tensorB])`
- Once we're done with a session, it should be closed
`session.close()`

4 Tensors

A tensor is simply a multidimensional array of data. A scalar is a 0-D tensor, a vector is a 1-D tensor, a matrix is a 2-D tensor and anything over 3-D is called an n-D tensor.

Rank: The number of dimensions of a tensor.

Rank	Math entity	Example
0	Scalar	$s = 483$
1	Vector	$v = [1.1, 2.2, 3.3]$
2	Matrix	$m = [[1, 2, 3], [4, 5, 6], [7, 8, 9]]$
3	3-Tensor	$t = [[[2], [4], [6]], [[8], [10], [12]], [[14], [16], [18]]]$

Shape: A vector describing the number of elements at each point within a dimension.

Rank	Shape	Dimension number	Example
0	[]	0-D	A 0-D tensor. A scalar.
1	[D0]	1-D	A 1-D tensor with shape [5] = [1, 2, 3, 4, 5].
2	[D0, D1]	2-D	A 2-D tensor with shape [3, 4] = [[1, 2, 3, 4], [1, 2, 3, 4], [1, 2, 3, 4]].
3	[D0, D1, D2]	3-D	A 3-D tensor with shape [1, 4, 3] = [[[1, 2, 3], [1, 2, 3], [1, 2, 3], [1, 2, 3]]].
n	[D0, D1, ..., Dn]	n-D	A tensor with shape [D0, D1, ..., Dn].

Type: Type of the data contained within the tensor.

Data type	Description
DT_FLOAT	32 bits floating point.
DT_DOUBLE	64 bits floating point.
DT_INT64	64 bits signed integer.
DT_INT32	32 bits signed integer.
DT_INT16	16 bits signed integer.
DT_INT8	8 bits signed integer.
DT_UINT8	8 bits unsigned integer.
DT_STRING	Variable length byte arrays. Each element of a Tensor is a byte array.
DT_BOOL	Boolean.
DT_COMPLEX64	Complex number made of two 32 bits floating points: real and imaginary parts.
DT_QINT32	32 bits signed integer used in quantized Ops.
DT_QINT8	8 bits signed integer used in quantized Ops.
DT_QUINT8	8 bits unsigned integer used in quantized Ops.

5 Variables

- Variables must be initialized (`tf.initialize_all_variables()`)
- Initialization is an operation, and thus must be executed within a session

6 Fetches

- All the ops needed to produce the values of requested tensors are run once (not once per requested tensor)

7 Feeds

- Temporarily replaces the output of an operation with a tensor value (act as a placeholder)
- The feed data is provided as an argument to a `session.run()` call
`sess.run([output], feed_dict={input1:[7.], input2:[2.]})`

8 Operations/Functions of interest

8.1 CNN

- `tf.nn.conv2d(input, kernel, strides, padding)`: apply a convolution using kernel
- `tf.nn.relu(input)`: rectifier linear unit, every negative value is set to 0, and positive values are kept the same
- `tf.sigmoid(input)`: returns a value in the range [0.0, 1.0]
- `tf.tanh(input)`: returns a value in the range [-1.0, 1.0]
- `tf.nn.dropout(input, keep_prob)`: set the output to 0.0 based on a given probability. The output is multiplied by $1/\text{keep_prob}$ in order to keep the expected sum unchanged
- `tf.nn.max_pool(input, kernel, strides, padding)`: take the maximum value found within a certain kernel size
- `tf.nn.avg_pool(input, kernel, strides, padding)`: averages out all the values at each depth found within a kernel size
- `tf.nn.local_response_normalization`

8.2 RNN

- `tf.nn.rnn_cell.BasicRNNCell(num_neurons)`: declares a recurrent neural network cell
- `tf.nn.dynamic_rnn(network, input)`: simulate the given RNN
- `tf.nn.rnn_cell.LSTMCell(num_neurons)`: declares a long short-term memory neural network cell
- `tf.nn.rnn_cell.GRUCell(num_neurons)`: declares a gated recurrent unit cell

9 CNN

- Used mostly to process high density matrices where the data surrounding a value is generally highly correlated with it
- Apply the convolution operator to a 2d matrix using a given kernel/filter

10 RNN

- Used to process sequential inputs (speech recognition, speech synthesis, connected handwriting recognition, time-series forecast, image caption generation, end-to-end translation)

11 See also

12 References

- <https://www.tensorflow.org/>
- <https://medium.com/jim-fleming/loading-tensorflow-graphs-via-host-languages-be10fd81876f>